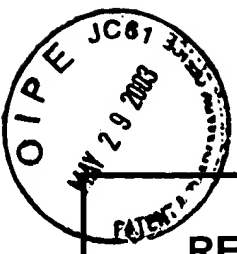


3661



S&H Form: (01/03)

<b>REPLY/AMENDMENT FEE TRANSMITTAL</b>	Attorney Docket No.	392.1627	
	Application Number	09/265,432	
	Filing Date	March 10, 1999	
	First Named Inventor	Akihiro TERADA et al.	
	Group Art Unit	3661	
AMOUNT ENCLOSED	0.00	Examiner Name	T. NGUYEN

**FEE CALCULATION (fees effective 01/01/03)**

CLAIMS AS AMENDED	Claims Remaining After Amendment	Highest Number Previously Paid For	Number Extra	Rate	Calculations
TOTAL CLAIMS	2	- 16 =	0	X \$ 18.00 =	\$ 0.00
INDEPENDENT CLAIMS	2	- 6 =	0	X \$ 84.00 =	0.00

Since an Official Action set an original due date of May 27, 2003, petition is hereby made for an extension to cover the date this reply is filed for which the requisite fee is enclosed (1 month (\$110); 2 months (\$410); 3 months (\$930); 4 months (\$1,450); 5 months (\$1,970)):

If Notice of Appeal is enclosed, add (\$320.00)

If Statutory Disclaimer under Rule 20(d) is enclosed, add fee (\$110.00)

Information Disclosure Statement (Rule 1.17(p)) (\$180.00)

Total of above Calculations =

\$ 0.00

Reduction by 50% for filing by small entity (37 CFR 1.9, 1.27 & 1.28)

TOTAL FEES DUE =

\$ 0.00

- (1) If entry (1) is less than entry (2), entry (3) is "0".
- (2) If entry (2) is less than 20, change entry (2) to "20".
- (4) If entry (4) is less than entry (5), entry (6) is "0".
- (5) If entry (5) is less than 3, change entry (5) to "3".

**RECEIVED**  
JUN 02 2003  
**GROUP 3661**

**METHOD OF PAYMENT**

- ☐ Check enclosed as payment.
- ☐ Charge "TOTAL FEES DUE" to the Deposit Account No. below.
- ☒ No payment is enclosed and no charges to the Deposit Account are authorized at this time (unless specifically required to obtain a filing date).

**GENERAL AUTHORIZATION**

- ☒ If the above-noted "AMOUNT ENCLOSED" is not correct, the Commissioner is hereby authorized to credit any overpayment or charge any additional fees necessary to:  
Deposit Account No. 19-3935  
Deposit Account Name STAAS & HALSEY LLP
- ☒ The Commissioner is also authorized to credit any overpayments or charge any additional fees required under 37 CFR 1.16 (filing fees) or 37 CFR 1.17 (processing fees) during the prosecution of this application, including any related application(s) claiming benefit hereof pursuant to 35 USC § 120 (e.g., continuations/divisionals/CIPs under 37 CFR 1.53(b) and/or continuations/divisionals/CPAs under 37 CFR 1.53(d)) to maintain pendency hereof or of any such related application.

SUBMITTED BY: STAAS & HALSEY LLP

Typed Name	Patrick J. Stanzione	Reg. No.	40,434
Signature		I hereby certify that this correspondence is being deposited with the United States Postal Service as first class mail in an envelope addressed to the Office of Patents and Trademarks, Washington, D.C. 20231	

CERTIFICATE UNDER 37 CFR 1.3(a)  
on MAY 27, 2003  
By: Patrick J. Stanzione  
Date: MAY 27, 2003



20  
C  
Cofler  
6-6-03  
Docket No.: 392.1627

IN THE UNITED STATES PATENT AND TRADEMARK OFFICE

In re the Application of:

Akihiro TERADA et al.

Serial No. 09/265,432

Group Art Unit: 3661

Confirmation No. 4506

Filed: March 10, 1999

Examiner: T. NGUYEN

For: ROBOT SYSTEM AND MACHINING METHOD WITH ROBOT SYSTEM

RECEIVED  
JUN 02 2003  
GROUP 3600

AMENDMENT

Commissioner for Patents  
PO Box 1450  
Alexandria, VA 22313-1450

Sir:

This is in response to the Office Action mailed February 27, 2003, and having a period for response set to expire on May 27, 2003.

The following amendments and remarks are respectfully submitted. Reconsideration of the claims is respectfully requested.

IN THE CLAIMS:

Please AMEND the following claims:

Sub D1  
C1  
1. (TWICE AMENDED) A robot system comprising:  
a movable arm including a plurality of links and a wrist connected by joints and controlled by a robot controller having a software processing function; and  
a tool unit mounted on said wrist at a distal end of said movable arm, and having an effecting end point biased with respect to a final rotational axis of said wrist and directed to said final rotational axis.

C2  
Cont  
9. (TWICE AMENDED) A method of machining a cylindrical workpiece with a robot